

D R A F T

Document for a Standard Message-Passing Interface

Message Passing Interface Forum

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Chapter 8

MPI Environmental Management

This chapter discusses routines for getting and, where appropriate, setting various parameters that relate to the MPI implementation and the execution environment (such as error handling). The procedures for entering and leaving the MPI execution environment are also described here.

8.1 Implementation Information

8.1.1 Version Inquiries

In order to cope with changes to the MPI Standard, there are both compile-time and run-time ways to determine which version of the standard is in use in the environment one is using.

The “version” will be represented by two separate integers, for the version and subversion: In C,

```
#define MPI_VERSION    3
#define MPI_SUBVERSION 1
```

in Fortran,

```
INTEGER :: MPI_VERSION, MPI_SUBVERSION
PARAMETER (MPI_VERSION    = 3)
PARAMETER (MPI_SUBVERSION = 1)
```

For runtime determination,

`MPI_GET_VERSION(version, subversion)`

OUT	version	version number (integer)
OUT	subversion	subversion number (integer)

```
int MPI_Get_version(int *version, int *subversion)
```

```
MPI_Get_version(version, subversion, ierror)
  INTEGER, INTENT(OUT) :: version, subversion
  INTEGER, OPTIONAL, INTENT(OUT) :: ierror
```

```

1 MPI_GET_VERSION(VERSION, SUBVERSION, IERROR)
2     INTEGER VERSION, SUBVERSION, IERROR

```

3 MPI_GET_VERSION can be called before MPI_INIT and after MPI_FINALIZE. This
4 function must always be thread-safe, as defined in Section 12.4. Valid (MPI_VERSION,
5 MPI_SUBVERSION) pairs in this and previous versions of the MPI standard are (3,1), (3,0),
6 (2,2), (2,1), (2,0), and (1,2).
7

```

9 MPI_GET_LIBRARY_VERSION(version, resultlen)

```

```

10     OUT     version           version string (string)
11
12     OUT     resultlen        Length (in printable characters) of the result returned
13                               in version (integer)

```

```

14
15 int MPI_Get_library_version(char *version, int *resultlen)

```

```

16 MPI_Get_library_version(version, resultlen, ierror)
17     CHARACTER(LEN=MPI_MAX_LIBRARY_VERSION_STRING), INTENT(OUT) :: version
18     INTEGER, INTENT(OUT) :: resultlen
19     INTEGER, OPTIONAL, INTENT(OUT) :: ierror

```

```

20
21 MPI_GET_LIBRARY_VERSION(VERSION, RESULTLEN, IERROR)
22     CHARACTER*(*) VERSION
23     INTEGER RESULTLEN, IERROR

```

24 This routine returns a string representing the version of the MPI library. The version
25 argument is a character string for maximum flexibility.
26

27 *Advice to implementors.* An implementation of MPI should return a different string
28 for every change to its source code or build that could be visible to the user. (*End of*
29 *advice to implementors.*)
30

31 The argument `version` must represent storage that is
32 MPI_MAX_LIBRARY_VERSION_STRING characters long. MPI_GET_LIBRARY_VERSION may
33 write up to this many characters into `version`.
34

35 The number of characters actually written is returned in the output argument, `resultlen`.
36 In C, a null character is additionally stored at `version[resultlen]`. The value of `resultlen` cannot
37 be larger than MPI_MAX_LIBRARY_VERSION_STRING - 1. In Fortran, `version` is padded on
38 the right with blank characters. The value of `resultlen` cannot be larger than
39 MPI_MAX_LIBRARY_VERSION_STRING.
40

41 MPI_GET_LIBRARY_VERSION can be called before MPI_INIT and after
42 MPI_FINALIZE. This function must always be thread-safe, as defined in Section 12.4.
43

8.1.2 Environmental Inquiries

44 A set of attributes that describe the execution environment are attached to the communi-
45 cator MPI_COMM_WORLD when MPI is initialized. The values of these attributes can be
46 inquired by using the function MPI_COMM_GET_ATTR described in Section 6.7 and in
47 Section 18.2.7. It is erroneous to delete these attributes, free their keys, or change their
48 values.

The list of predefined attribute keys include

MPI_TAG_UB Upper bound for tag value.

MPI_HOST Host process rank, if such exists, MPI_PROC_NULL, otherwise.

MPI_IO rank of a node that has regular I/O facilities (possibly myrank). Nodes in the same communicator may return different values for this parameter.

MPI_WTIME_IS_GLOBAL Boolean variable that indicates whether clocks are synchronized.

Vendors may add implementation-specific parameters (such as node number, real memory size, virtual memory size, etc.)

These predefined attributes do not change value between MPI initialization (MPI_INIT) and MPI completion (MPI_FINALIZE), and cannot be updated or deleted by users.

Advice to users. Note that in the C binding, the value returned by these attributes is a *pointer* to an `int` containing the requested value. (*End of advice to users.*)

The required parameter values are discussed in more detail below:

Tag Values

Tag values range from 0 to the value returned for MPI_TAG_UB, inclusive. These values are guaranteed to be unchanging during the execution of an MPI program. In addition, the tag upper bound value must be *at least* 32767. An MPI implementation is free to make the value of MPI_TAG_UB larger than this; for example, the value $2^{30} - 1$ is also a valid value for MPI_TAG_UB.

The attribute MPI_TAG_UB has the same value on all processes of MPI_COMM_WORLD.

Host Rank

The value returned for MPI_HOST gets the rank of the *HOST* process in the group associated with communicator MPI_COMM_WORLD, if there is such. MPI_PROC_NULL is returned if there is no host. MPI does not specify what it means for a process to be a *HOST*, nor does it require that a *HOST* exists.

The attribute MPI_HOST has the same value on all processes of MPI_COMM_WORLD.

IO Rank

The value returned for MPI_IO is the rank of a processor that can provide language-standard I/O facilities. For Fortran, this means that all of the Fortran I/O operations are supported (e.g., OPEN, REWIND, WRITE). For C, this means that all of the ISO C I/O operations are supported (e.g., fopen, fprintf, lseek).

If every process can provide language-standard I/O, then the value MPI_ANY_SOURCE will be returned. Otherwise, if the calling process can provide language-standard I/O, then its rank will be returned. Otherwise, if some process can provide language-standard I/O then the rank of one such process will be returned. The same value need not be returned by all processes. If no process can provide language-standard I/O, then the value MPI_PROC_NULL will be returned.

Advice to users. Note that input is not collective, and this attribute does *not* indicate which process can or does provide input. (*End of advice to users.*)

1 Clock Synchronization

2 The value returned for `MPI_WTIME_IS_GLOBAL` is 1 if clocks at all processes in
 3 `MPI_COMM_WORLD` are synchronized, 0 otherwise. A collection of clocks is considered
 4 synchronized if explicit effort has been taken to synchronize them. The expectation is that
 5 the variation in time, as measured by calls to `MPI_WTIME`, will be less than one half the
 6 round-trip time for an MPI message of length zero. If time is measured at a process just
 7 before a send and at another process just after a matching receive, the second time should
 8 be always higher than the first one.

9 The attribute `MPI_WTIME_IS_GLOBAL` need not be present when the clocks are not
 10 synchronized (however, the attribute key `MPI_WTIME_IS_GLOBAL` is always valid). This
 11 attribute may be associated with communicators other than `MPI_COMM_WORLD`.

12 The attribute `MPI_WTIME_IS_GLOBAL` has the same value on all processes of
 13 `MPI_COMM_WORLD`.

15 Inquire Processor Name

18 `MPI_GET_PROCESSOR_NAME(name, resultlen)`

20	OUT	name	A unique specifier for the actual (as opposed to virtual) node.
22	OUT	resultlen	Length (in printable characters) of the result returned in name

25 `int MPI_Get_processor_name(char *name, int *resultlen)`

27 `MPI_Get_processor_name(name, resultlen, ierror)`
 28 CHARACTER(LEN=MPI_MAX_PROCESSOR_NAME), INTENT(OUT) :: name
 29 INTEGER, INTENT(OUT) :: resultlen
 30 INTEGER, OPTIONAL, INTENT(OUT) :: ierror

31 `MPI_GET_PROCESSOR_NAME(NAME, RESULTLEN, IERROR)`
 32 CHARACTER*(*) NAME
 33 INTEGER RESULTLEN, IERROR

35 This routine returns the name of the processor on which it was called at the moment
 36 of the call. The name is a character string for maximum flexibility. From this value it
 37 must be possible to identify a specific piece of hardware; possible values include “processor
 38 9 in rack 4 of mpp.cs.org” and “231” (where 231 is the actual processor number in the
 39 running homogeneous system). The argument `name` must represent storage that is at least
 40 `MPI_MAX_PROCESSOR_NAME` characters long. `MPI_GET_PROCESSOR_NAME` may write
 41 up to this many characters into `name`.

42 The number of characters actually written is returned in the output argument, `resultlen`.
 43 In C, a null character is additionally stored at `name[resultlen]`. The value of `resultlen` cannot
 44 be larger than `MPI_MAX_PROCESSOR_NAME-1`. In Fortran, `name` is padded on the right with
 45 blank characters. The value of `resultlen` cannot be larger than `MPI_MAX_PROCESSOR_NAME`.

46
 47 *Rationale.* This function allows MPI implementations that do process migration to
 48 return the current processor. Note that nothing in MPI *requires* or defines process

migration; this definition of MPI_GET_PROCESSOR_NAME simply allows such an implementation. (*End of rationale.*)

Advice to users. The user must provide at least MPI_MAX_PROCESSOR_NAME space to write the processor name — processor names can be this long. The user should examine the output argument, resultlen, to determine the actual length of the name. (*End of advice to users.*)

Inquire Hardware Resource Names

There are two possible designs for this routine:

- a local version: with 2 subdesigns (in purple)
 - return the types to which the calling process is bound
 - return all possible types, need a supplemental info key
- a collective version

MPI_GET_HW_SUBDOMAIN_TYPES(hw_info)

OUT hw_info new info object (handle)

```
int MPI_Get_hw_subdomain_types(MPI_Info *hw_info)
```

```
MPI_Get_hw_subdomain_types(hw_info, ierror)
    TYPE(MPI_Info), INTENT(OUT) :: hw_info
    INTEGER, OPTIONAL, INTENT(OUT) :: ierror
```

```
MPI_GET_HWSUBDOMAIN_TYPES(HW_INFO, IERROR)
    HW_INFO, IERROR
```

This routine returns an info object containing information pertaining to the hardware platform on which the calling MPI process is executing at the moment of the call. The information available is stored in the following info keys:

- mpi_hw_res_nresources is an integer that represents the number of hardware resource types recognized by the MPI implementation and to which the calling MPI process is/can be restricted.
- mpi_hw_res_i_type is the type of the i -th hardware resource to which the calling MPI process is/can be restricted (with $i \in \{0, \dots, \text{mpi_hw_res_nresources} - 1\}$).
- mpi_hw_res_i_aliases is an integer that represents the number of hardware resource types that are aliases to mpi_hw_res_i_type (with $i \in \{0, \dots, \text{mpi_hw_res_nresources} - 1\}$).
- mpi_hw_res_i_alias_k with $k \in \{0, \dots, \text{mpi_hw_res_i_aliases} - 1\}$ is an integer j (with $j \in \{0, \dots, \text{mpi_hw_res_nresources} - 1\}$) such that mpi_hw_res_j_type is an alias to mpi_hw_res_i_type.

- `mpi_hw_res_i_occupied`, where $i \in \{0, \dots, \text{mpi_hw_res_nresources} - 1\}$, is true if the calling MPI process is restricted to hardware resource number i at the moment of the call.

OR:

`MPI_GET_HW_SUBDOMAIN_TYPES(comm, hw_info)`

IN	<code>comm</code>	intracommunicator (handle)
OUT	<code>hw_info</code>	new info object (handle)

`int MPI_Get_hw_subdomain_types(MPI_Comm comm, MPI_Info *hw_info)`

`MPI_Get_hw_subdomain_types(comm, hw_info, ierror)`

TYPE(MPI_Comm), INTENT(IN) :: `comm`
 TYPE(MPI_Info), INTENT(OUT) :: `hw_info`
 INTEGER, OPTIONAL, INTENT(OUT) :: `ierror`

`MPI_GET_HW_SUBDOMAIN_TYPES(COMM, HW_INFO, IERROR)`

INTEGER COMM, HW_INFO, IERROR

This routine returns an info object that contains information about the hardware resources that are usable by the MPI processes members of the group associated with `comm` at the time of the call.

Advice to users. On heterogeneous hardware, some of the provided hardware resource types may be not valid for all MPI processes. (*End of advice to users.*)

This routine is collective and returns the same information in the process group of `comm`. The information available is stored in the following info keys:

- `mpi_hw_res_nresources` is an integer that represents the number of hardware resource types recognized by the MPI implementation and to which the calling MPI process may be restricted.
- `mpi_hw_res_i_type` is the type of the i -th hardware resource to which the calling MPI process can be restricted (with $i \in \{0, \dots, \text{mpi_hw_res_nresources} - 1\}$).
- `mpi_hw_res_i_aliases` is an integer that represents the number of hardware resource types that are aliases to `mpi_hw_res_i_type` (with $i \in \{0, \dots, \text{mpi_hw_res_nresources} - 1\}$).
- `mpi_hw_res_i_alias_k` with $k \in \{0, \dots, \text{mpi_hw_res_i_aliases} - 1\}$ is an integer j (with $j \in \{0, \dots, \text{mpi_hw_res_nresources} - 1\}$) such that `mpi_hw_res_j_type` is an alias to `mpi_hw_res_i_type`.
- `mpi_hw_res_i_occupied`, where $i \in \{0, \dots, \text{mpi_hw_res_nresources} - 1\}$, is true if the calling MPI process is restricted to hardware resource number i at the moment of the call.

The following text applies to both designs:

The user is responsible for freeing `hw_info` via `MPI_INFO_FREE`.

Advice to users. The types returned by this routine can be used in `MPI_COMM_SPLIT_TYPE` as key values for the info key `mpi_hw_subdomain_type`. However, the information returned in `hw_info` may not be constant throughout the execution of the program because an MPI process can relocate (e.g., migrate or change its hardware restrictions). (*End of advice to users.*)

8.2 Memory Allocation

In some systems, message-passing and remote-memory-access (RMA) operations run faster when accessing specially allocated memory (e.g., memory that is shared by the other processes in the communicating group on an SMP). MPI provides a mechanism for allocating and freeing such special memory. The use of such memory for message-passing or RMA is not mandatory, and this memory can be used without restrictions as any other dynamically allocated memory. However, implementations may restrict the use of some RMA functionality as defined in Section 11.5.3.

`MPI_ALLOC_MEM(size, info, baseptr)`

IN	size	size of memory segment in bytes (non-negative integer)
IN	info	info argument (handle)
OUT	baseptr	pointer to beginning of memory segment allocated

```
int MPI_Alloc_mem(MPI_Aint size, MPI_Info info, void *baseptr)
```

```
MPI_Alloc_mem(size, info, baseptr, ierror)
  USE, INTRINSIC :: ISO_C_BINDING, ONLY : C_PTR
  INTEGER(KIND=MPI_ADDRESS_KIND), INTENT(IN) :: size
  TYPE(MPI_Info), INTENT(IN) :: info
  TYPE(C_PTR), INTENT(OUT) :: baseptr
  INTEGER, OPTIONAL, INTENT(OUT) :: ierror
```

```
MPI_ALLOC_MEM(SIZE, INFO, BASEPTR, IERROR)
  INTEGER INFO, IERROR
  INTEGER(KIND=MPI_ADDRESS_KIND) SIZE, BASEPTR
```

If the Fortran compiler provides `TYPE(C_PTR)`, then the following generic interface must be provided in the `mpi` module and should be provided in `mpif.h` through overloading, i.e., with the same routine name as the routine with `INTEGER(KIND=MPI_ADDRESS_KIND) BASEPTR`, but with a different specific procedure name:

```
INTERFACE MPI_ALLOC_MEM
  SUBROUTINE MPI_ALLOC_MEM(SIZE, INFO, BASEPTR, IERROR)
    IMPORT :: MPI_ADDRESS_KIND
    INTEGER INFO, IERROR
    INTEGER(KIND=MPI_ADDRESS_KIND) SIZE, BASEPTR
  END SUBROUTINE
```

```

1  SUBROUTINE MPI_ALLOC_MEM_CPTR(SIZE, INFO, BASEPTR, IERROR)
2      USE, INTRINSIC :: ISO_C_BINDING, ONLY : C_PTR
3      IMPORT :: MPI_ADDRESS_KIND
4      INTEGER :: INFO, IERROR
5      INTEGER(KIND=MPI_ADDRESS_KIND) :: SIZE
6      TYPE(C_PTR) :: BASEPTR
7  END SUBROUTINE
8  END INTERFACE

```

The base procedure name of this overloaded function is `MPI_ALLOC_MEM_CPTR`. The implied specific procedure names are described in Section 18.1.5.

The `info` argument can be used to provide directives that control the desired location of the allocated memory. Such a directive does not affect the semantics of the call. Valid `info` values are implementation-dependent; a null directive value of `info = MPI_INFO_NULL` is always valid.

The function `MPI_ALLOC_MEM` may return an error code of class `MPI_ERR_NO_MEM` to indicate it failed because memory is exhausted.

`MPI_FREE_MEM(base)`

IN	base	initial address of memory segment allocated by <code>MPI_ALLOC_MEM</code> (choice)
----	------	---

```
int MPI_Free_mem(void *base)
```

```

MPI_Free_mem(base, ierror)
  TYPE(*), DIMENSION(..), INTENT(IN), ASYNCHRONOUS :: base
  INTEGER, OPTIONAL, INTENT(OUT) :: ierror

```

`MPI_FREE_MEM(BASE, IERROR)`

```

<type> BASE(*)
INTEGER IERROR

```

The function `MPI_FREE_MEM` may return an error code of class `MPI_ERR_BASE` to indicate an invalid base argument.

Rationale. The C bindings of `MPI_ALLOC_MEM` and `MPI_FREE_MEM` are similar to the bindings for the `malloc` and `free` C library calls: a call to `MPI_Alloc_mem(..., &base)` should be paired with a call to `MPI_Free_mem(base)` (one less level of indirection). Both arguments are declared to be of same type `void*` so as to facilitate type casting. The Fortran binding is consistent with the C bindings: the Fortran `MPI_ALLOC_MEM` call returns in `baseptr` the `TYPE(C_PTR)` pointer or the (integer valued) address of the allocated memory. The `base` argument of `MPI_FREE_MEM` is a choice argument, which passes (a reference to) the variable stored at that location. (*End of rationale.*)

Advice to implementors. If `MPI_ALLOC_MEM` allocates special memory, then a design similar to the design of C `malloc` and `free` functions has to be used, in order to find out the size of a memory segment, when the segment is freed. If no special

memory is used, `MPI_ALLOC_MEM` simply invokes `malloc`, and `MPI_FREE_MEM` invokes `free`.

A call to `MPI_ALLOC_MEM` can be used in shared memory systems to allocate memory in a shared memory segment. (*End of advice to implementors.*)

Example 8.1 Example of use of `MPI_ALLOC_MEM`, in Fortran with `TYPE(C_PTR)` pointers. We assume 4-byte REALs.

```

USE mpi_f08 ! or USE mpi      (not guaranteed with INCLUDE 'mpif.h')
USE, INTRINSIC :: ISO_C_BINDING
TYPE(C_PTR) :: p
REAL, DIMENSION(:,:), POINTER :: a ! no memory is allocated
INTEGER, DIMENSION(2) :: shape
INTEGER(KIND=MPI_ADDRESS_KIND) :: size
shape = (/100,100/)
size = 4 * shape(1) * shape(2) ! assuming 4 bytes per REAL
CALL MPI_Alloc_mem(size,MPI_INFO_NULL,p,ierr) ! memory is allocated and
CALL C_F_POINTER(p, a, shape) ! intrinsic ! now accessible via a(i,j)
... ! in ISO_C_BINDING
a(3,5) = 2.71;
...
CALL MPI_Free_mem(a, ierr) ! memory is freed

```

Example 8.2 Example of use of `MPI_ALLOC_MEM`, in Fortran with non-standard *Cray-pointers*. We assume 4-byte REALs, and assume that these pointers are address-sized.

```

REAL A
POINTER (P, A(100,100)) ! no memory is allocated
INTEGER(KIND=MPI_ADDRESS_KIND) SIZE
SIZE = 4*100*100
CALL MPI_ALLOC_MEM(SIZE, MPI_INFO_NULL, P, IERR)
! memory is allocated
...
A(3,5) = 2.71;
...
CALL MPI_FREE_MEM(A, IERR) ! memory is freed

```

This code is not Fortran 77 or Fortran 90 code. Some compilers may not support this code or need a special option, e.g., the GNU gFortran compiler needs `-fcray-pointer`.

Advice to implementors. Some compilers map Cray-pointers to address-sized integers, some to `TYPE(C_PTR)` pointers (e.g., Cray Fortran, version 7.3.3). From the user's viewpoint, this mapping is irrelevant because Examples 8.2 should work correctly with an MPI-3.0 (or later) library if Cray-pointers are available. (*End of advice to implementors.*)

Example 8.3 Same example, in C.

```

1   float (*f)[100][100];
2   /* no memory is allocated */
3   MPI_Alloc_mem(sizeof(float)*100*100, MPI_INFO_NULL, &f);
4   /* memory allocated */
5   ...
6   (*f)[5][3] = 2.71;
7   ...
8   MPI_Free_mem(f);

```

8.3 Error Handling

An MPI implementation cannot or may choose not to handle some errors that occur during MPI calls. These can include errors that generate exceptions or traps, such as floating point errors or access violations. The set of errors that are handled by MPI is implementation-dependent. Each such error generates an **MPI exception**.

The above text takes precedence over any text on error handling within this document. Specifically, text that states that errors *will* be handled should be read as *may* be handled. More background information about how MPI treats errors can be found in Section 2.8.

A user can associate error handlers to three types of objects: communicators, windows, and files. The specified error handling routine will be used for any MPI exception that occurs during a call to MPI for the respective object. MPI calls that are not related to any objects are considered to be attached to the communicator MPI_COMM_SELF. When MPI_COMM_SELF is not initialized (i.e., before MPI_INIT / MPI_INIT_THREAD or after MPI_FINALIZE) the error raises the initial error handler (set during the launch operation, see 10.3.4). The attachment of error handlers to objects is purely local: different processes may attach different error handlers to corresponding objects.

Several predefined error handlers are available in MPI:

MPI_ERRORS_ARE_FATAL The handler, when called, causes the program to abort all connected MPI processes. This is similar to calling MPI_ABORT using a communicator containing all connected processes with an implementation-specific value as the `errorcode` argument.

MPI_ERRORS_ABORT The handler, when called, is invoked on a communicator in a manner similar to calling MPI_ABORT on that communicator. If the error handler is invoked on an window or a file, it is similar to calling MPI_ABORT using a communicator containing the group of MPI processes associated with the window or file, respectively. In either case, the value that would be provided as the `errorcode` argument to MPI_ABORT is implementation-specific.

MPI_ERRORS_RETURN The handler has no effect other than returning the error code to the user.

Advice to implementors. The implementation-specific error information resulting from MPI_ERRORS_ARE_FATAL and MPI_ERRORS_ABORT provided to the invoking environment should be meaningful to the end-user, for example a predefined error class. (*End of advice to implementors.*)

Implementations may provide additional predefined error handlers and programmers can code their own error handlers.

Unless otherwise requested, the error handler `MPI_ERRORS_ARE_FATAL` is set as the default initial error handler and associated with predefined communicators. Thus, if the user chooses not to control error handling, every error that MPI handles is treated as fatal. Since (almost) all MPI calls return an error code, a user may choose to handle errors in its main code, by testing the return code of MPI calls and executing a suitable recovery code when the call was not successful. In this case, the error handler `MPI_ERRORS_RETURN` will be used. Usually it is more convenient and more efficient not to test for errors after each MPI call, and have such error handled by a non-trivial MPI error handler. Note that unlike predefined communicators, windows and files do not inherit from the initial error handler, as defined in Sections 11.6 and 13.7 respectively.

After an error is detected, MPI will provide the user as much information as possible about that error using error classes. Some errors might prevent MPI from completing further API calls successfully and those functions will continue to report errors until the cause of the error is corrected or the user terminates the application. The user can make the determination of whether or not to attempt to continue after detecting such an error.

Advice to users. For example, users may be unable to correct errors corresponding to some error classes, such as `MPI_ERR_INTERN`. Such errors may cause subsequent MPI calls to complete in error. (*End of advice to users.*)

Advice to implementors. A high-quality implementation will, to the greatest possible extent, circumscribe the impact of an error, so that normal processing can continue after an error handler was invoked. The implementation documentation will provide information on the possible effect of each class of errors and available recovery actions. (*End of advice to implementors.*)

An MPI error handler is an opaque object, which is accessed by a handle. MPI calls are provided to create new error handlers, to associate error handlers with objects, and to test which error handler is associated with an object. C has distinct typedefs for user defined error handling callback functions that accept communicator, file, and window arguments. In Fortran there are three user routines.

An error handler object is created by a call to `MPI_XXX_CREATE_ERRHANDLER`, where XXX is, respectively, `COMM`, `WIN`, or `FILE`.

An error handler is attached to a communicator, window, or file by a call to `MPI_XXX_SET_ERRHANDLER`. The error handler must be either a predefined error handler, or an error handler that was created by a call to `MPI_XXX_CREATE_ERRHANDLER`, with matching XXX. The predefined error handlers `MPI_ERRORS_RETURN` and `MPI_ERRORS_ARE_FATAL` can be attached to communicators, windows, and files.

The error handler currently associated with a communicator, window, or file can be retrieved by a call to `MPI_XXX_GET_ERRHANDLER`.

The MPI function `MPI_ERRHANDLER_FREE` can be used to free an error handler that was created by a call to `MPI_XXX_CREATE_ERRHANDLER`.

`MPI_{COMM,WIN,FILE}_GET_ERRHANDLER` behave as if a new error handler object is created. That is, once the error handler is no longer needed, `MPI_ERRHANDLER_FREE` should be called with the error handler returned from `MPI_{COMM,WIN,FILE}_GET_ERRHANDLER` to mark the error handler for deallocation. This provides behavior similar to that of `MPI_COMM_GROUP` and `MPI_GROUP_FREE`.

1 *Advice to implementors.* High-quality implementations should raise an error when
 2 an error handler that was created by a call to `MPI_XXX_CREATE_ERRHANDLER` is
 3 attached to an object of the wrong type with a call to `MPI_YYY_SET_ERRHANDLER`.
 4 To do so, it is necessary to maintain, with each error handler, information on the
 5 typedef of the associated user function. (*End of advice to implementors.*)

6 The syntax for these calls is given below.

8.3.1 Error Handlers for Communicators

```

11 MPI_COMM_CREATE_ERRHANDLER(comm_errhandler_fn, errhandler)
12
13     IN      comm_errhandler_fn      user defined error handling procedure (function)
14     OUT    errhandler              MPI error handler (handle)
15
16
17 int MPI_Comm_create_errhandler(MPI_Comm_errhandler_function
18                               *comm_errhandler_fn, MPI_Errhandler *errhandler)
19
20 MPI_Comm_create_errhandler(comm_errhandler_fn, errhandler, ierror)
21     PROCEDURE(MPI_Comm_errhandler_function) :: comm_errhandler_fn
22     TYPE(MPI_Errhandler), INTENT(OUT) :: errhandler
23     INTEGER, OPTIONAL, INTENT(OUT) :: ierror
24
25 MPI_COMM_CREATE_ERRHANDLER(COMM_ERRHANDLER_FN, ERRHANDLER, IERROR)
26     EXTERNAL COMM_ERRHANDLER_FN
27     INTEGER ERRHANDLER, IERROR
  
```

27 Creates an error handler that can be attached to communicators.

28 The user routine should be, in C, a function of type `MPI_Comm_errhandler_function`, which
 29 is defined as

```

30 typedef void MPI_Comm_errhandler_function(MPI_Comm *, int *, ...);
  
```

31
 32 The first argument is the communicator in use. The second is the error code to be
 33 returned by the MPI routine that raised the error. If the routine would have returned
 34 `MPI_ERR_IN_STATUS`, it is the error code returned in the status for the request that caused
 35 the error handler to be invoked. The remaining arguments are “`varargs`” arguments whose
 36 number and meaning is implementation-dependent. An implementation should clearly docu-
 37 ment these arguments. Addresses are used so that the handler may be written in Fortran.
 38 With the Fortran `mpi_f08` module, the user routine `comm_errhandler_fn` should be of the
 39 form:

```

40 ABSTRACT INTERFACE
41     SUBROUTINE MPI_Comm_errhandler_function(comm, error_code)
42         TYPE(MPI_Comm) :: comm
43         INTEGER :: error_code
  
```

44 With the Fortran `mpi` module and `mpif.h`, the user routine `COMM_ERRHANDLER_FN`
 45 should be of the form:

```

46 SUBROUTINE COMM_ERRHANDLER_FUNCTION(COMM, ERROR_CODE)
47     INTEGER COMM, ERROR_CODE
  
```

Rationale. The variable argument list is provided because it provides an ISO-standard hook for providing additional information to the error handler; without this hook, ISO C prohibits additional arguments. (*End of rationale.*)

Advice to users. A newly created communicator inherits the error handler that is associated with the “parent” communicator. In particular, the user can specify a “global” error handler for all communicators by associating this handler with the communicator MPI_COMM_WORLD immediately after initialization. (*End of advice to users.*)

MPI_COMM_SET_ERRHANDLER(comm, errhandler)

INOUT	comm	communicator (handle)
IN	errhandler	new error handler for communicator (handle)

int MPI_Comm_set_errhandler(MPI_Comm comm, MPI_Errhandler errhandler)

```
MPI_Comm_set_errhandler(comm, errhandler, ierror)
    TYPE(MPI_Comm), INTENT(IN) :: comm
    TYPE(MPI_Errhandler), INTENT(IN) :: errhandler
    INTEGER, OPTIONAL, INTENT(OUT) :: ierror
```

```
MPI_COMM_SET_ERRHANDLER(COMM, ERRHANDLER, IERROR)
    INTEGER COMM, ERRHANDLER, IERROR
```

Attaches a new error handler to a communicator. The error handler must be either a predefined error handler, or an error handler created by a call to MPI_COMM_CREATE_ERRHANDLER.

MPI_COMM_GET_ERRHANDLER(comm, errhandler)

IN	comm	communicator (handle)
OUT	errhandler	error handler currently associated with communicator (handle)

int MPI_Comm_get_errhandler(MPI_Comm comm, MPI_Errhandler *errhandler)

```
MPI_Comm_get_errhandler(comm, errhandler, ierror)
    TYPE(MPI_Comm), INTENT(IN) :: comm
    TYPE(MPI_Errhandler), INTENT(OUT) :: errhandler
    INTEGER, OPTIONAL, INTENT(OUT) :: ierror
```

```
MPI_COMM_GET_ERRHANDLER(COMM, ERRHANDLER, IERROR)
    INTEGER COMM, ERRHANDLER, IERROR
```

Retrieves the error handler currently associated with a communicator.

For example, a library function may register at its entry point the current error handler for a communicator, set its own private error handler for this communicator, and restore before exiting the previous error handler.

8.3.2 Error Handlers for Windows

```

1 MPI_WIN_CREATE_ERRHANDLER(win_errhandler_fn, errhandler)
2
3
4 MPI_WIN_CREATE_ERRHANDLER(win_errhandler_fn, errhandler)

```

```

5     IN        win_errhandler_fn        user defined error handling procedure (function)
6
7     OUT       errhandler                MPI error handler (handle)
8

```

```

9 int MPI_Win_create_errhandler(MPI_Win_errhandler_function
10                             *win_errhandler_fn, MPI_Errhandler *errhandler)
11

```

```

12 MPI_Win_create_errhandler(win_errhandler_fn, errhandler, ierror)
13     PROCEDURE(MPI_Win_errhandler_function) :: win_errhandler_fn
14     TYPE(MPI_Errhandler), INTENT(OUT) :: errhandler
15     INTEGER, OPTIONAL, INTENT(OUT) :: ierror
16

```

```

17 MPI_WIN_CREATE_ERRHANDLER(WIN_ERRHANDLER_FN, ERRHANDLER, IERROR)
18     EXTERNAL WIN_ERRHANDLER_FN
19     INTEGER ERRHANDLER, IERROR
20

```

Creates an error handler that can be attached to a window object. The user routine should be, in C, a function of type `MPI_Win_errhandler_function` which is defined as

```

21 typedef void MPI_Win_errhandler_function(MPI_Win *, int *, ...);
22

```

The first argument is the window in use, the second is the error code to be returned. With the Fortran `mpi_f08` module, the user routine `win_errhandler_fn` should be of the form:

```

23 ABSTRACT INTERFACE
24     SUBROUTINE MPI_Win_errhandler_function(win, error_code)
25         TYPE(MPI_Win) :: win
26         INTEGER :: error_code
27
28
29

```

With the Fortran `mpi` module and `mpif.h`, the user routine `WIN_ERRHANDLER_FN` should be of the form:

```

30 SUBROUTINE WIN_ERRHANDLER_FUNCTION(WIN, ERROR_CODE)
31     INTEGER WIN, ERROR_CODE
32
33
34

```

```

35 MPI_WIN_SET_ERRHANDLER(win, errhandler)
36

```

```

37     INOUT    win                        window (handle)
38
39     IN       errhandler                new error handler for window (handle)
40

```

```

41 int MPI_Win_set_errhandler(MPI_Win win, MPI_Errhandler errhandler)
42

```

```

43 MPI_Win_set_errhandler(win, errhandler, ierror)
44     TYPE(MPI_Win), INTENT(IN) :: win
45     TYPE(MPI_Errhandler), INTENT(IN) :: errhandler
46     INTEGER, OPTIONAL, INTENT(OUT) :: ierror
47

```

```

48 MPI_WIN_SET_ERRHANDLER(WIN, ERRHANDLER, IERROR)
49     INTEGER WIN, ERRHANDLER, IERROR

```


Attaches a new error handler to a window. The error handler must be either a pre-defined error handler, or an error handler created by a call to `MPI_WIN_CREATE_ERRHANDLER`.

`MPI_WIN_GET_ERRHANDLER(win, errhandler)`

IN	win	window (handle)	
OUT	errhandler	error handler currently associated with window (handle)	

```
int MPI_Win_get_errhandler(MPI_Win win, MPI_Errhandler *errhandler)
```

```
MPI_Win_get_errhandler(win, errhandler, ierror)
  TYPE(MPI_Win), INTENT(IN) :: win
  TYPE(MPI_Errhandler), INTENT(OUT) :: errhandler
  INTEGER, OPTIONAL, INTENT(OUT) :: ierror
```

```
MPI_WIN_GET_ERRHANDLER(WIN, ERRHANDLER, IERROR)
  INTEGER WIN, ERRHANDLER, IERROR
```

Retrieves the error handler currently associated with a window.

8.3.3 Error Handlers for Files

`MPI_FILE_CREATE_ERRHANDLER(file_errhandler_fn, errhandler)`

IN	file_errhandler_fn	user defined error handling procedure (function)
OUT	errhandler	MPI error handler (handle)

```
int MPI_File_create_errhandler(MPI_File_errhandler_function
  *file_errhandler_fn, MPI_Errhandler *errhandler)
```

```
MPI_File_create_errhandler(file_errhandler_fn, errhandler, ierror)
  PROCEDURE(MPI_File_errhandler_function) :: file_errhandler_fn
  TYPE(MPI_Errhandler), INTENT(OUT) :: errhandler
  INTEGER, OPTIONAL, INTENT(OUT) :: ierror
```

```
MPI_FILE_CREATE_ERRHANDLER(FILE_ERRHANDLER_FN, ERRHANDLER, IERROR)
  EXTERNAL FILE_ERRHANDLER_FN
  INTEGER ERRHANDLER, IERROR
```

Creates an error handler that can be attached to a file object. The user routine should be, in C, a function of type `MPI_File_errhandler_function`, which is defined as

```
typedef void MPI_File_errhandler_function(MPI_File *, int *, ...);
```

The first argument is the file in use, the second is the error code to be returned. With the Fortran `mpi_f08` module, the user routine `file_errhandler_fn` should be of the form:

```
ABSTRACT INTERFACE
```

```
  SUBROUTINE MPI_File_errhandler_function(file, error_code)
```

```

1     TYPE(MPI_File) :: file
2     INTEGER :: error_code

```

3 With the Fortran `mpi` module and `mpif.h`, the user routine `FILE_ERRHANDLER_FN` should
4 be of the form:

```

5 SUBROUTINE FILE_ERRHANDLER_FUNCTION(FILE, ERROR_CODE)
6     INTEGER FILE, ERROR_CODE
7
8
9

```

```

10 MPI_FILE_SET_ERRHANDLER(file, errhandler)

```

```

11     INOUT  file                file (handle)
12     IN     errhandler         new error handler for file (handle)
13
14

```

```

15 int MPI_File_set_errhandler(MPI_File file, MPI_Errhandler errhandler)

```

```

16 MPI_File_set_errhandler(file, errhandler, ierror)
17     TYPE(MPI_File), INTENT(IN) :: file
18     TYPE(MPI_Errhandler), INTENT(IN) :: errhandler
19     INTEGER, OPTIONAL, INTENT(OUT) :: ierror
20
21

```

```

22 MPI_FILE_SET_ERRHANDLER(FILE, ERRHANDLER, IERROR)
23     INTEGER FILE, ERRHANDLER, IERROR
24
25

```

26 Attaches a new error handler to a file. The error handler must be either a predefined
27 error handler, or an error handler created by a call to `MPI_FILE_CREATE_ERRHANDLER`.
28
29

```

30 MPI_FILE_GET_ERRHANDLER(file, errhandler)

```

```

31     IN     file                file (handle)
32     OUT    errhandler         error handler currently associated with file (handle)
33
34

```

```

35 int MPI_File_get_errhandler(MPI_File file, MPI_Errhandler *errhandler)

```

```

36 MPI_File_get_errhandler(file, errhandler, ierror)
37     TYPE(MPI_File), INTENT(IN) :: file
38     TYPE(MPI_Errhandler), INTENT(OUT) :: errhandler
39     INTEGER, OPTIONAL, INTENT(OUT) :: ierror
40
41

```

```

42 MPI_FILE_GET_ERRHANDLER(FILE, ERRHANDLER, IERROR)
43     INTEGER FILE, ERRHANDLER, IERROR
44
45

```

46 Retrieves the error handler currently associated with a file.
47
48

8.3.4 Freeing Errorhandlers and Retrieving Error Strings

```
MPI_ERRHANDLER_FREE(errhandler)
```

```
    INOUT    errhandler                MPI error handler (handle)
```

```
int MPI_Errhandler_free(MPI_Errhandler *errhandler)
```

```
MPI_Errhandler_free(errhandler, ierror)
    TYPE(MPI_Errhandler), INTENT(INOUT) :: errhandler
    INTEGER, OPTIONAL, INTENT(OUT) :: ierror
```

```
MPI_ERRHANDLER_FREE(ERRHANDLER, IERROR)
    INTEGER ERRHANDLER, IERROR
```

Marks the error handler associated with `errhandler` for deallocation and sets `errhandler` to `MPI_ERRHANDLER_NULL`. The error handler will be deallocated after all the objects associated with it (communicator, window, or file) have been deallocated.

```
MPI_ERROR_STRING(errorcode, string, resultlen)
```

```
    IN        errorcode                Error code returned by an MPI routine
    OUT       string                   Text that corresponds to the errorcode
    OUT       resultlen                Length (in printable characters) of the result returned
                                         in string
```

```
int MPI_Error_string(int errorcode, char *string, int *resultlen)
```

```
MPI_Error_string(errorcode, string, resultlen, ierror)
    INTEGER, INTENT(IN) :: errorcode
    CHARACTER(LEN=MPI_MAX_ERROR_STRING), INTENT(OUT) :: string
    INTEGER, INTENT(OUT) :: resultlen
    INTEGER, OPTIONAL, INTENT(OUT) :: ierror
```

```
MPI_ERROR_STRING(ERRORCODE, STRING, RESULTLEN, IERROR)
    INTEGER ERRORCODE, RESULTLEN, IERROR
    CHARACTER*(*) STRING
```

Returns the error string associated with an error code or class. The argument `string` must represent storage that is at least `MPI_MAX_ERROR_STRING` characters long.

The number of characters actually written is returned in the output argument, `resultlen`.

This function must always be thread-safe, as defined in Section 12.4. It is one of the few routines that may be called before MPI is initialized or after MPI is finalized.

Rationale. The form of this function was chosen to make the Fortran and C bindings similar. A version that returns a pointer to a string has two difficulties. First, the return string must be statically allocated and different for each error message (allowing the pointers returned by successive calls to `MPI_ERROR_STRING` to point to the

correct message). Second, in Fortran, a function declared as returning CHARACTER*(*) can not be referenced in, for example, a PRINT statement. (*End of rationale.*)

8.4 Error Codes and Classes

The error codes returned by MPI are left entirely to the implementation (with the exception of MPI_SUCCESS). This is done to allow an implementation to provide as much information as possible in the error code (for use with MPI_ERROR_STRING).

To make it possible for an application to interpret an error code, the routine MPI_ERROR_CLASS converts any error code into one of a small set of standard error codes, called *error classes*. Valid error classes are shown in Table 8.1 and Table 8.2.

The error classes are a subset of the error codes: an MPI function may return an error class number; and the function MPI_ERROR_STRING can be used to compute the error string associated with an error class. The values defined for MPI error classes are valid MPI error codes.

The error codes satisfy,

$$0 = \text{MPI_SUCCESS} < \text{MPI_ERR_}\dots \leq \text{MPI_ERR_LASTCODE}.$$

Rationale. The difference between MPI_ERR_UNKNOWN and MPI_ERR_OTHER is that MPI_ERROR_STRING can return useful information about MPI_ERR_OTHER.

Note that MPI_SUCCESS = 0 is necessary to be consistent with C practice; the separation of error classes and error codes allows us to define the error classes this way. Having a known LASTCODE is often a nice sanity check as well. (*End of rationale.*)

```
MPI_ERROR_CLASS(errorcode, errorclass)
```

IN	errorcode	Error code returned by an MPI routine
OUT	errorclass	Error class associated with errorcode

```
int MPI_Error_class(int errorcode, int *errorclass)
```

```
MPI_Error_class(errorcode, errorclass, ierror)
```

```
INTEGER, INTENT(IN) :: errorcode
INTEGER, INTENT(OUT) :: errorclass
INTEGER, OPTIONAL, INTENT(OUT) :: ierror
```

```
MPI_ERROR_CLASS(ERRORCODE, ERRORCLASS, IERROR)
```

```
INTEGER ERRORCODE, ERRORCLASS, IERROR
```

The function MPI_ERROR_CLASS maps each standard error code (error class) onto itself.

This function must always be thread-safe, as defined in Section 12.4. It is one of the few routines that may be called before MPI is initialized or after MPI is finalized.

		1
		2
MPI_SUCCESS	No error	3
MPI_ERR_BUFFER	Invalid buffer pointer	4
MPI_ERR_COUNT	Invalid count argument	5
MPI_ERR_TYPE	Invalid datatype argument	6
MPI_ERR_TAG	Invalid tag argument	7
MPI_ERR_COMM	Invalid communicator	8
MPI_ERR_RANK	Invalid rank	9
MPI_ERR_REQUEST	Invalid request (handle)	10
MPI_ERR_ROOT	Invalid root	11
MPI_ERR_GROUP	Invalid group	12
MPI_ERR_OP	Invalid operation	13
MPI_ERR_TOPOLOGY	Invalid topology	14
MPI_ERR_DIMS	Invalid dimension argument	15
MPI_ERR_ARG	Invalid argument of some other kind	16
MPI_ERR_UNKNOWN	Unknown error	17
MPI_ERR_TRUNCATE	Message truncated on receive	18
MPI_ERR_OTHER	Known error not in this list	19
MPI_ERR_INTERN	Internal MPI (implementation) error	20
MPI_ERR_IN_STATUS	Error code is in status	21
MPI_ERR_PENDING	Pending request	22
MPI_ERR_KEYVAL	Invalid keyval has been passed	23
MPI_ERR_NO_MEM	MPI_ALLOC_MEM failed because memory is exhausted	24
MPI_ERR_BASE	Invalid base passed to MPI_FREE_MEM	25
MPI_ERR_INFO_KEY	Key longer than MPI_MAX_INFO_KEY	26
MPI_ERR_INFO_VALUE	Value longer than MPI_MAX_INFO_VAL	27
MPI_ERR_INFO_NOKEY	Invalid key passed to MPI_INFO_DELETE	28
MPI_ERR_SPAWN	Error in spawning processes	29
MPI_ERR_PORT	Invalid port name passed to MPI_COMM_CONNECT	30
MPI_ERR_SERVICE	Invalid service name passed to MPI_UNPUBLISH_NAME	31
MPI_ERR_NAME	Invalid service name passed to MPI_LOOKUP_NAME	32
MPI_ERR_WIN	Invalid win argument	33
MPI_ERR_SIZE	Invalid size argument	34
MPI_ERR_DISP	Invalid disp argument	35
MPI_ERR_INFO	Invalid info argument	36
MPI_ERR_LOCKTYPE	Invalid locktype argument	37
MPI_ERR_ASSERT	Invalid assert argument	38
MPI_ERR_RMA_CONFLICT	Conflicting accesses to window	39
MPI_ERR_RMA_SYNC	Wrong synchronization of RMA calls	40
		41
		42
		43
		44
		45
		46
		47
		48

Table 8.1: Error classes (Part 1)

1		
2		
3		
4	MPI_ERR_RMA_RANGE	Target memory is not part of the win-
5		dow (in the case of a window created
6		with MPI_WIN_CREATE_DYNAMIC, tar-
7		get memory is not attached)
8	MPI_ERR_RMA_ATTACH	Memory cannot be attached (e.g., because
9		of resource exhaustion)
10	MPI_ERR_RMA_SHARED	Memory cannot be shared (e.g., some pro-
11		cess in the group of the specified commu-
12		nicator cannot expose shared memory)
13	MPI_ERR_RMA_FLAVOR	Passed window has the wrong flavor for the
14		called function
15	MPI_ERR_FILE	Invalid file handle
16	MPI_ERR_NOT_SAME	Collective argument not identical on all
17		processes, or collective routines called in
18		a different order by different processes
19	MPI_ERR_AMODE	Error related to the amode passed to
20		MPI_FILE_OPEN
21	MPI_ERR_UNSUPPORTED_DATAREP	Unsupported datarep passed to
22		MPI_FILE_SET_VIEW
23	MPI_ERR_UNSUPPORTED_OPERATION	Unsupported operation, such as seeking on
24		a file which supports sequential access only
25	MPI_ERR_NO_SUCH_FILE	File does not exist
26	MPI_ERR_FILE_EXISTS	File exists
27	MPI_ERR_BAD_FILE	Invalid file name (e.g., path name too long)
28	MPI_ERR_ACCESS	Permission denied
29	MPI_ERR_NO_SPACE	Not enough space
30	MPI_ERR_QUOTA	Quota exceeded
31	MPI_ERR_READ_ONLY	Read-only file or file system
32	MPI_ERR_FILE_IN_USE	File operation could not be completed, as
33		the file is currently open by some process
34	MPI_ERR_DUP_DATAREP	Conversion functions could not be regis-
35		tered because a data representation identi-
36		fier that was already defined was passed to
37		MPI_REGISTER_DATAREP
38	MPI_ERR_CONVERSION	An error occurred in a user supplied data
39		conversion function.
40	MPI_ERR_IO	Other I/O error
41	MPI_ERR_LASTCODE	Last error code
42		
43		
44		
45		
46		
47		
48		

Table 8.2: Error classes (Part 2)

8.5 Error Classes, Error Codes, and Error Handlers

Users may want to write a layered library on top of an existing MPI implementation, and this library may have its own set of error codes and classes. An example of such a library is an I/O library based on MPI, see Chapter 13. For this purpose, functions are needed to:

1. add a new error class to the ones an MPI implementation already knows.
2. associate error codes with this error class, so that `MPI_ERROR_CLASS` works.
3. associate strings with these error codes, so that `MPI_ERROR_STRING` works.
4. invoke the error handler associated with a communicator, window, or object.

Several functions are provided to do this. They are all local. No functions are provided to free error classes or codes: it is not expected that an application will generate them in significant numbers.

```
MPI_ADD_ERROR_CLASS(errorclass)
```

```
OUT    errorclass                value for the new error class (integer)
```

```
int MPI_Add_error_class(int *errorclass)
```

```
MPI_Add_error_class(errorclass, ierror)
    INTEGER, INTENT(OUT) :: errorclass
    INTEGER, OPTIONAL, INTENT(OUT) :: ierror
```

```
MPI_ADD_ERROR_CLASS(ERRORCLASS, IERROR)
    INTEGER ERRORCLASS, IERROR
```

Creates a new error class and returns the value for it.

Rationale. To avoid conflicts with existing error codes and classes, the value is set by the implementation and not by the user. (*End of rationale.*)

Advice to implementors. A high-quality implementation will return the value for a new `errorclass` in the same deterministic way on all processes. (*End of advice to implementors.*)

Advice to users. Since a call to `MPI_ADD_ERROR_CLASS` is local, the same `errorclass` may not be returned on all processes that make this call. Thus, it is not safe to assume that registering a new error on a set of processes at the same time will yield the same `errorclass` on all of the processes. However, if an implementation returns the new `errorclass` in a deterministic way, and they are always generated in the same order on the same set of processes (for example, all processes), then the value will be the same. However, even if a deterministic algorithm is used, the value can vary across processes. This can happen, for example, if different but overlapping groups of processes make a series of calls. As a result of these issues, getting the “same” error on multiple processes may not cause the same value of error code to be generated. (*End of advice to users.*)

1 The value of `MPI_ERR_LASTCODE` is a constant value and is not affected by new user-
 2 defined error codes and classes. Instead, a predefined attribute key `MPI_LASTUSED` is
 3 associated with `MPI_COMM_WORLD`. The attribute value corresponding to this key is the
 4 current maximum error class including the user-defined ones. This is a local value and may
 5 be different on different processes. The value returned by this key is always greater than or
 6 equal to `MPI_ERR_LASTCODE`.

7
 8 *Advice to users.* The value returned by the key `MPI_LASTUSED` will not change
 9 unless the user calls a function to explicitly add an error class/code. In a multi-
 10 threaded environment, the user must take extra care in assuming this value has not
 11 changed. Note that error codes and error classes are not necessarily dense. A user
 12 may not assume that each error class below `MPI_LASTUSED` is valid. (*End of*
 13 *advice to users.*)

14
 15
 16 `MPI_ADD_ERROR_CODE(errorclass, errorcode)`

17 IN errorclass error class (integer)
 18 OUT errorcode new error code to associated with errorclass (integer)

19
 20
 21 `int MPI_Add_error_code(int errorclass, int *errorcode)`

22
 23 `MPI_Add_error_code(errorclass, errorcode, ierror)`

24 INTEGER, INTENT(IN) :: errorclass
 25 INTEGER, INTENT(OUT) :: errorcode
 26 INTEGER, OPTIONAL, INTENT(OUT) :: ierror

27 `MPI_ADD_ERROR_CODE(ERRORCLASS, ERRORCODE, IERROR)`

28 INTEGER ERRORCLASS, ERRORCODE, IERROR

29
 30 Creates new error code associated with `errorclass` and returns its value in `errorcode`.

31
 32 *Rationale.* To avoid conflicts with existing error codes and classes, the value of the
 33 new error code is set by the implementation and not by the user. (*End of rationale.*)

34
 35 *Advice to implementors.* A high-quality implementation will return the value for
 36 a new `errorcode` in the same deterministic way on all processes. (*End of advice to*
 37 *implementors.*)

38
 39
 40 `MPI_ADD_ERROR_STRING(errorcode, string)`

41 IN errorcode error code or class (integer)
 42 IN string text corresponding to errorcode (string)

43
 44
 45 `int MPI_Add_error_string(int errorcode, const char *string)`

46 `MPI_Add_error_string(errorcode, string, ierror)`

47 INTEGER, INTENT(IN) :: errorcode
 48


```

    CHARACTER(LEN=*), INTENT(IN) :: string           1
    INTEGER, OPTIONAL, INTENT(OUT) :: ierror        2
MPI_ADD_ERROR_STRING(ERRORCODE, STRING, IERROR)    3
    INTEGER ERRORCODE, IERROR                       4
    CHARACTER*(*) STRING                           5
                                                    6

```

Associates an error string with an error code or class. The string must be no more than `MPI_MAX_ERROR_STRING` characters long. The length of the string is as defined in the calling language. The length of the string does not include the null terminator in C. Trailing blanks will be stripped in Fortran. Calling `MPI_ADD_ERROR_STRING` for an errorcode that already has a string will replace the old string with the new string. It is erroneous to call `MPI_ADD_ERROR_STRING` for an error code or class with a value \leq `MPI_ERR_LASTCODE`.

If `MPI_ERROR_STRING` is called when no string has been set, it will return a empty string (all spaces in Fortran, "" in C).

Section 8.3 describes the methods for creating and associating error handlers with communicators, files, and windows.

```

MPI_COMM_CALL_ERRHANDLER(comm, errorcode)          18
                                                    19
    IN      comm          communicator with error handler (handle) 20
    IN      errorcode     error code (integer)                    21
                                                    22

```

```

int MPI_Comm_call_errhandler(MPI_Comm comm, int errorcode) 23
                                                    24
MPI_Comm_call_errhandler(comm, errorcode, ierror) 25
    TYPE(MPI_Comm), INTENT(IN) :: comm                    26
    INTEGER, INTENT(IN) :: errorcode                     27
    INTEGER, OPTIONAL, INTENT(OUT) :: ierror              28
                                                    29

```

```

MPI_COMM_CALL_ERRHANDLER(COMM, ERRORCODE, IERROR) 30
    INTEGER COMM, ERRORCODE, IERROR                     31
                                                    32

```

This function invokes the error handler assigned to the communicator with the error code supplied. This function returns `MPI_SUCCESS` in C and the same value in `IERROR` if the error handler was successfully called (assuming the process is not aborted and the error handler returns).

```

MPI_WIN_CALL_ERRHANDLER(win, errorcode)           37
                                                    38
    IN      win           window with error handler (handle)    39
    IN      errorcode     error code (integer)                  40
                                                    41

```

```

int MPI_Win_call_errhandler(MPI_Win win, int errorcode) 42
                                                    43
MPI_Win_call_errhandler(win, errorcode, ierror) 44
    TYPE(MPI_Win), INTENT(IN) :: win                      45
    INTEGER, INTENT(IN) :: errorcode                       46
    INTEGER, OPTIONAL, INTENT(OUT) :: ierror               47
                                                    48

```

```

1 MPI_WIN_CALL_ERRHANDLER(WIN, ERRORCODE, IERROR)
2     INTEGER WIN, ERRORCODE, IERROR

```

This function invokes the error handler assigned to the window with the error code supplied. This function returns `MPI_SUCCESS` in C and the same value in `IERROR` if the error handler was successfully called (assuming the process is not aborted and the error handler returns).

Advice to users. In contrast to communicators, the error handler `MPI_ERRORS_ARE_FATAL` is associated with a window when it is created. (*End of advice to users.*)

```

13 MPI_FILE_CALL_ERRHANDLER(fh, errorcode)

```

```

14     IN      fh                file with error handler (handle)
15
16     IN      errorcode        error code (integer)

```

```

18 int MPI_File_call_errhandler(MPI_File fh, int errorcode)

```

```

19 MPI_File_call_errhandler(fh, errorcode, ierror)
20     TYPE(MPI_File), INTENT(IN) :: fh
21     INTEGER, INTENT(IN) :: errorcode
22     INTEGER, OPTIONAL, INTENT(OUT) :: ierror

```

```

24 MPI_FILE_CALL_ERRHANDLER(FH, ERRORCODE, IERROR)
25     INTEGER FH, ERRORCODE, IERROR

```

This function invokes the error handler assigned to the file with the error code supplied. This function returns `MPI_SUCCESS` in C and the same value in `IERROR` if the error handler was successfully called (assuming the process is not aborted and the error handler returns).

Advice to users. Unlike errors on communicators and windows, the default behavior for files is to have `MPI_ERRORS_RETURN`. (*End of advice to users.*)

Advice to users. Users are warned that handlers should not be called recursively with `MPI_COMM_CALL_ERRHANDLER`, `MPI_FILE_CALL_ERRHANDLER`, or `MPI_WIN_CALL_ERRHANDLER`. Doing this can create a situation where an infinite recursion is created. This can occur if `MPI_COMM_CALL_ERRHANDLER`, `MPI_FILE_CALL_ERRHANDLER`, or `MPI_WIN_CALL_ERRHANDLER` is called inside an error handler.

Error codes and classes are associated with a process. As a result, they may be used in any error handler. Error handlers should be prepared to deal with any error code they are given. Furthermore, it is good practice to only call an error handler with the appropriate error codes. For example, file errors would normally be sent to the file error handler. (*End of advice to users.*)

8.6 Timers and Synchronization

MPI defines a timer. A timer is specified even though it is not “message-passing,” because timing parallel programs is important in “performance debugging” and because existing

timers (both in POSIX 1003.1-1988 and 1003.4D 14.1 and in Fortran 90) are either inconvenient or do not provide adequate access to high resolution timers. See also Section 2.6.4.

MPI_WTIME()

```
double MPI_Wtime(void)
```

```
DOUBLE PRECISION MPI_Wtime()
```

```
DOUBLE PRECISION MPI_WTIME()
```

MPI_WTIME returns a floating-point number of seconds, representing elapsed wall-clock time since some time in the past.

The “time in the past” is guaranteed not to change during the life of the process. The user is responsible for converting large numbers of seconds to other units if they are preferred.

This function is portable (it returns seconds, not “ticks”), it allows high-resolution, and carries no unnecessary baggage. One would use it like this:

```
{
    double starttime, endtime;
    starttime = MPI_Wtime();
    .... stuff to be timed ...
    endtime = MPI_Wtime();
    printf("That took %f seconds\n",endtime-starttime);
}
```

The times returned are local to the node that called them. There is no requirement that different nodes return “the same time.” (But see also the discussion of MPI_WTIME_IS_GLOBAL in Section 8.1.2).

MPI_WTICK()

```
double MPI_Wtick(void)
```

```
DOUBLE PRECISION MPI_Wtick()
```

```
DOUBLE PRECISION MPI_WTICK()
```

MPI_WTICK returns the resolution of MPI_WTIME in seconds. That is, it returns, as a double precision value, the number of seconds between successive clock ticks. For example, if the clock is implemented by the hardware as a counter that is incremented every millisecond, the value returned by MPI_WTICK should be 10^{-3} .

8.7 Startup

One goal of MPI is to achieve *source code portability*. By this we mean that a program written using MPI and complying with the relevant language standards is portable as written, and must not require any source code changes when moved from one system to another. This explicitly does *not* say anything about how an MPI program is started or launched from

1 the command line, nor what the user must do to set up the environment in which an MPI
 2 program will run. However, an implementation may require some setup to be performed
 3 before other MPI routines may be called. To provide for this, MPI includes an initialization
 4 routine `MPI_INIT`.

```

5
6 MPI_INIT()
7
8 int MPI_Init(int *argc, char ***argv)
9
10 MPI_Init(ierror)
11     INTEGER, OPTIONAL, INTENT(OUT) :: ierror
12
13 MPI_INIT(IERROR)
14     INTEGER IERROR
  
```

15 All MPI programs must contain exactly one call to an MPI initialization routine:
 16 `MPI_INIT` or `MPI_INIT_THREAD`. Subsequent calls to any initialization routines are erro-
 17 neous. The only MPI functions that may be invoked before the MPI initialization routines
 18 are called are `MPI_GET_VERSION`, `MPI_GET_LIBRARY_VERSION`, `MPI_INITIALIZED`,
 19 `MPI_FINALIZED`, `MPI_ERROR_CLASS`, `MPI_ERROR_STRING`, and any function with the
 20 prefix `MPI_T_` (within the constraints for functions with this prefix listed in Section 14.3.4).
 21 The version for ISO C accepts the `argc` and `argv` that are provided by the arguments to `main`
 22 or `NULL`:

```

23
24 int main(int argc, char *argv[])
25 {
26     MPI_Init(&argc, &argv);
27
28     /* parse arguments */
29     /* main program */
30
31     MPI_Finalize();    /* see below */
32     return 0;
33 }
  
```

34 The Fortran version takes only `IERROR`.

35 Conforming implementations of MPI are required to allow applications to pass `NULL`
 36 for both the `argc` and `argv` arguments of `main` in C.

37 Failures may disrupt the execution of the program before or during MPI initialization.
 38 A high-quality implementation shall not deadlock during MPI initialization, even in the
 39 presence of failures. Except for functions with the `MPI_T_` prefix, failures in MPI operations
 40 prior to or during MPI initialization are reported by invoking the initial error handler.
 41 Users can use the `mpi_initial_errhandler` info key during the launch of MPI processes (e.g.,
 42 `MPI_COMM_SPAWN / MPI_COMM_SPAWN_MULTIPLE`, or `mpiexec`) to set a non-fatal
 43 initial error handler before MPI initialization. When the initial error handler is set to
 44 `MPI_ERRORS_ABORT`, raising an error before or during initialization aborts the local MPI
 45 process (i.e., it is similar to calling `MPI_ABORT` on `MPI_COMM_SELF`). An implementation
 46 may not always be capable of determining, before MPI initialization, what constitutes the
 47 local MPI process, or the set of connected processes. In this case, errors before initialization
 48

may cause a different set of MPI processes to abort than specified. After MPI initialization, the initial error handler is associated with `MPI_COMM_WORLD`, `MPI_COMM_SELF`, and the communicator returned by `MPI_COMM_GET_PARENT` (if any).

Advice to implementors. Some failures may leave MPI in an undefined state, or raise an error before the error handling capabilities are fully operational, in which cases the implementation may be incapable of providing the desired error handling behavior. Of note, in some implementations, the notion of an MPI process is not clearly established in the early stages of MPI initialization (for example, when the implementation considers threads that called `MPI_INIT` as independent MPI processes); in this case, before MPI is initialized, the `MPI_ERRORS_ABORT` error handler may abort what would have become multiple MPI processes.

When a failure occurs during MPI initialization, the implementation may decide to return `MPI_SUCCESS` from the MPI initialization function instead of raising an error. It is recommended that an implementation masks an initialization error only when it expects that later MPI calls will result in well specified behavior (i.e., barring additional failures, either the outcome of any call will be correct, or the call will raise an appropriate error). For example, it may be difficult for an implementation to avoid unspecified behavior when the group of `MPI_COMM_WORLD` does not contain the same set of MPI processes at all members of the communicator, or if the communicator returned from `MPI_COMM_GET_PARENT` was not initialized correctly. (*End of advice to implementors.*)

While MPI is initialized, the application can access information about the execution environment by querying the predefined info object `MPI_INFO_ENV`. The following keys are predefined for this object, corresponding to the arguments of `MPI_COMM Spawn` or of `mpiexec`:

`command` Name of program executed.

`argv` Space separated arguments to command.

`maxprocs` Maximum number of MPI processes to start.

`mpi_initial_errhandler` Name of the initial errhandler.

`soft` Allowed values for number of processors.

`host` Hostname.

`arch` Architecture name.

`wdir` Working directory of the MPI process.

`file` Value is the name of a file in which additional information is specified.

`thread_level` Requested level of thread support, if requested before the program started execution.

Note that all values are strings. Thus, the maximum number of processes is represented by a string such as "1024" and the requested level is represented by a string such as "MPI_THREAD_SINGLE".

1 The info object `MPI_INFO_ENV` need not contain a (key,value) pair for each of these
 2 predefined keys; the set of (key,value) pairs provided is implementation-dependent. Imple-
 3 mentations may provide additional, implementation specific, (key,value) pairs.

4 In case where the MPI processes were started with `MPI_COMM_SPAWN_MULTIPLE`
 5 or, equivalently, with a startup mechanism that supports multiple process specifications,
 6 then the values stored in the info object `MPI_INFO_ENV` at a process are those values that
 7 affect the local MPI process.

8
 9 **Example 8.4** If MPI is started with a call to

```
10 mpiexec -n 5 -arch sun ocean : -n 10 -arch rs6000 atmos
```

11 Then the first 5 processes will have in their `MPI_INFO_ENV` object the pairs (command,
 12 ocean), (maxprocs, 5), and (arch, sun). The next 10 processes will have in `MPI_INFO_ENV`
 13 (command, atmos), (maxprocs, 10), and (arch, rs6000)

14
 15 *Advice to users.* The values passed in `MPI_INFO_ENV` are the values of the arguments
 16 passed to the mechanism that started the MPI execution — not the actual value
 17 provided. Thus, the value associated with `maxprocs` is the number of MPI processes
 18 requested; it can be larger than the actual number of processes obtained, if the `soft`
 19 option was used. (*End of advice to users.*)

20
 21 *Advice to implementors.* High-quality implementations will provide a (key,value) pair
 22 for each parameter that can be passed to the command that starts an MPI program.
 23 (*End of advice to implementors.*)

24 MPI_FINALIZE()

```
25  

  26  

  27 int MPI_Finalize(void)  

  28  

  29 MPI_Finalize(ierror)  

  30     INTEGER, OPTIONAL, INTENT(OUT) :: ierror  

  31  

  32 MPI_FINALIZE(IERROR)  

  33     INTEGER IERROR
```

34 This routine cleans up all MPI state. If an MPI program terminates normally (i.e.,
 35 not due to a call to `MPI_ABORT` or an unrecoverable error) then each process must call
 36 `MPI_FINALIZE` before it exits.

37 Before an MPI process invokes `MPI_FINALIZE`, the process must perform all MPI calls
 38 needed to complete its involvement in MPI communications: It must locally complete all
 39 MPI operations that it initiated and must execute matching calls needed to complete MPI
 40 communications initiated by other processes. For example, if the process executed a non-
 41 blocking send, it must eventually call `MPI_WAIT`, `MPI_TEST`, `MPI_REQUEST_FREE`, or
 42 any derived function; if the process is the target of a send, then it must post the matching
 43 receive; if it is part of a group executing a collective operation, then it must have completed
 44 its participation in the operation.

45 The call to `MPI_FINALIZE` does not free objects created by MPI calls; these objects are
 46 freed using `MPI_XXX_FREE` calls.

47 `MPI_FINALIZE` is collective over all connected processes. If no processes were spawned,
 48 accepted or connected then this means over `MPI_COMM_WORLD`; otherwise it is collective

over the union of all processes that have been and continue to be connected, as explained in Section 10.5.4.

The following examples illustrate these rules

Example 8.5 The following code is correct

Process 0	Process 1
-----	-----
MPI_Init();	MPI_Init();
MPI_Send(dest=1);	MPI_Recv(src=0);
MPI_Finalize();	MPI_Finalize();

Example 8.6 Without a matching receive, the program is erroneous

Process 0	Process 1
-----	-----
MPI_Init();	MPI_Init();
MPI_Send (dest=1);	
MPI_Finalize();	MPI_Finalize();

Example 8.7 This program is correct: Process 0 calls MPI_Finalize after it has executed the MPI calls that complete the send operation. Likewise, process 1 executes the MPI call that completes the matching receive operation before it calls MPI_Finalize.

Process 0	Process 1
-----	-----
MPI_Init();	MPI_Init();
MPI_Isend(dest=1);	MPI_Recv(src=0);
MPI_Request_free();	MPI_Finalize();
MPI_Finalize();	exit();
exit();	

Example 8.8 This program is correct. The attached buffer is a resource allocated by the user, not by MPI; it is available to the user after MPI is finalized.

Process 0	Process 1
-----	-----
MPI_Init();	MPI_Init();
buffer = malloc(1000000);	MPI_Recv(src=0);
MPI_Buffer_attach();	MPI_Finalize();
MPI_Send(dest=1));	exit();
MPI_Finalize();	
free(buffer);	
exit();	

Example 8.9 This program is correct. The cancel operation must succeed, since the send cannot complete normally. The wait operation, after the call to MPI_Cancel, is local — no matching MPI call is required on process 1. Cancelling a send request by calling MPI_CANCEL is deprecated.

```

1
2     Process 0                               Process 1
3     -----                               -----
4     MPI_Issend(dest=1);                     MPI_Finalize();
5     MPI_Cancel();
6     MPI_Wait();
7     MPI_Finalize();

```

8
9 *Advice to implementors.* Even though a process has executed all MPI calls needed to
10 complete the communications it is involved with, such communication may not yet be
11 completed from the viewpoint of the underlying MPI system. For example, a blocking
12 send may have returned, even though the data is still buffered at the sender in an MPI
13 buffer; an MPI process may receive a cancel request for a message it has completed
14 receiving. The MPI implementation must ensure that a process has completed any
15 involvement in MPI communication before MPI_FINALIZE returns. Thus, if a process
16 exits after the call to MPI_FINALIZE, this will not cause an ongoing communication
17 to fail. The MPI implementation should also complete freeing all objects marked for
18 deletion by MPI calls that freed them. (*End of advice to implementors.*)

19
20 Once MPI_FINALIZE returns, no MPI routine (not even MPI_INIT) may be called,
21 except for MPI_GET_VERSION, MPI_GET_LIBRARY_VERSION, MPI_INITIALIZED,
22 MPI_FINALIZED, MPI_ERROR_CLASS, MPI_ERROR_STRING, and any function with the
23 prefix MPI_T_ (within the constraints for functions with this prefix listed in Section 14.3.4).

24 Failures may disrupt MPI operations during and after MPI finalization. A high quality
25 implementation shall not deadlock in MPI finalization, even in the presence of failures. The
26 normal rules for MPI error handling continue to apply. After MPI_COMM_SELF has been
27 “freed” (see 8.7.1), errors that are not associated with a communicator, window, or file raise
28 the initial error handler (set during the launch operation, see 10.3.4).

29 Although it is not required that all processes return from MPI_FINALIZE, it is required
30 that, when it has not failed or aborted, at least the MPI process that was assigned rank 0
31 in MPI_COMM_WORLD returns, so that users can know that the MPI portion of the com-
32 putation is over. In addition, in a POSIX environment, users may desire to supply an exit
33 code for each process that returns from MPI_FINALIZE.

34 Note that a failure may terminate the MPI process that was assigned rank 0 in
35 MPI_COMM_WORLD, in which case it is possible that no MPI process returns from
36 MPI_FINALIZE.

37
38 *Advice to users.* Applications that handle errors are encouraged to implement all
39 rank-specific code before the call to MPI_FINALIZE. In Example 8.10 below, the pro-
40 cess with rank 0 in MPI_COMM_WORLD may have been terminated before, during,
41 or after the call to MPI_FINALIZE, possibly leading to the code after MPI_FINALIZE
42 never being executed. (*End of advice to users.*)

43
44 **Example 8.10** The following illustrates the use of requiring that at least one process
45 return and that it be known that process 0 is one of the processes that return. One wants
46 code like the following to work no matter how many processes return.

47
48


```

...
MPI_Comm_rank(MPI_COMM_WORLD, &myrank);
...
MPI_Finalize();
if (myrank == 0) {
    resultfile = fopen("outfile", "w");
    dump_results(resultfile);
    fclose(resultfile);
}
exit(0);

```

MPI_INITIALIZED(flag)
 OUT flag Flag is true if MPI_INIT has been called and false otherwise.

```

int MPI_Initialized(int *flag)
MPI_Initialized(flag, ierror)
    LOGICAL, INTENT(OUT) :: flag
    INTEGER, OPTIONAL, INTENT(OUT) :: ierror
MPI_INITIALIZED(FLAG, IERROR)
    LOGICAL FLAG
    INTEGER IERROR

```

This routine may be used to determine whether MPI_INIT has been called. MPI_INITIALIZED returns true if the calling process has called MPI_INIT. Whether MPI_FINALIZE has been called does not affect the behavior of MPI_INITIALIZED. It is one of the few routines that may be called before MPI_INIT is called. This function must always be thread-safe, as defined in Section [12.4](#).

```

MPI_ABORT(comm, errorcode)
    IN          comm                      communicator of tasks to abort
    IN          errorcode                 error code to return to invoking environment

```

```

int MPI_Abort(MPI_Comm comm, int errorcode)
MPI_Abort(comm, errorcode, ierror)
    TYPE(MPI_Comm), INTENT(IN) :: comm
    INTEGER, INTENT(IN) :: errorcode
    INTEGER, OPTIONAL, INTENT(OUT) :: ierror
MPI_ABORT(COMM, ERRORCODE, IERROR)
    INTEGER COMM, ERRORCODE, IERROR

```

This routine makes a “best attempt” to abort all tasks in the group of comm. This function does not require that the invoking environment take any action with the error

1 code. However, a Unix or POSIX environment should handle this as a `return errorcode`
2 from the main program.

3 It may not be possible for an MPI implementation to abort only the processes repre-
4 sented by `comm` if this is a subset of the processes. In this case, the MPI implementation
5 should attempt to abort all the connected processes but should not abort any unconnected
6 processes. If no processes were spawned, accepted, or connected then this has the effect of
7 aborting all the processes associated with `MPI_COMM_WORLD`.

8
9 *Advice to implementors.* After aborting a subset of processes, a high quality im-
10 plementation should be able to provide error handling for communicators, windows,
11 and files involving both aborted and non-aborted processes. As an example, if the
12 user changes the error handler for `MPI_COMM_WORLD` to `MPI_ERRORS_RETURN` or a
13 custom error handler, when a subset of `MPI_COMM_WORLD` is aborted, the remaining
14 processes in `MPI_COMM_WORLD` should be able to continue communicating with each
15 other and receive appropriate error codes when attempting communication with an
16 aborted process. (*End of advice to implementors.*)

17
18 *Advice to users.* Whether the `errorcode` is returned from the executable or from the
19 MPI process startup mechanism (e.g., `mpiexec`), is an aspect of quality of the MPI
20 library but not mandatory. (*End of advice to users.*)

21
22 *Advice to implementors.* Where possible, a high-quality implementation will try
23 to return the `errorcode` from the MPI process startup mechanism (e.g. `mpiexec` or
24 `singleton init`). (*End of advice to implementors.*)

25 26 8.7.1 Allowing User Functions at Process Termination

27
28 There are times in which it would be convenient to have actions happen when an MPI process
29 finishes. For example, a routine may do initializations that are useful until the MPI job (or
30 that part of the job that being terminated in the case of dynamically created processes) is
31 finished. This can be accomplished in MPI by attaching an attribute to `MPI_COMM_SELF`
32 with a callback function. When `MPI_FINALIZE` is called, it will first execute the equivalent
33 of an `MPI_COMM_FREE` on `MPI_COMM_SELF`. This will cause the delete callback function
34 to be executed on all keys associated with `MPI_COMM_SELF`, in the reverse order that
35 they were set on `MPI_COMM_SELF`. If no key has been attached to `MPI_COMM_SELF`, then
36 no callback is invoked. The “freeing” of `MPI_COMM_SELF` occurs before any other parts
37 of MPI are affected. Thus, for example, calling `MPI_FINALIZED` will return `false` in any
38 of these callback functions. Once done with `MPI_COMM_SELF`, the order and rest of the
39 actions taken by `MPI_FINALIZE` is not specified.

40
41 *Advice to implementors.* Since attributes can be added from any supported language,
42 the MPI implementation needs to remember the creating language so the correct
43 callback is made. Implementations that use the attribute delete callback on
44 `MPI_COMM_SELF` internally should register their internal callbacks before returning
45 from `MPI_INIT` / `MPI_INIT_THREAD`, so that libraries or applications will not have
46 portions of the MPI implementation shut down before the application-level callbacks
47 are made. (*End of advice to implementors.*)

8.7.2 Determining Whether MPI Has Finished

One of the goals of MPI was to allow for layered libraries. In order for a library to do this cleanly, it needs to know if MPI is active. In MPI the function `MPI_INITIALIZED` was provided to tell if MPI had been initialized. The problem arises in knowing if MPI has been finalized. Once MPI has been finalized it is no longer active and cannot be restarted. A library needs to be able to determine this to act accordingly. To achieve this the following function is needed:

`MPI_FINALIZED(flag)`

OUT flag true if MPI was finalized (logical)

`int MPI_Finalized(int *flag)`

`MPI_Finalized(flag, ierror)`

LOGICAL, INTENT(OUT) :: flag

INTEGER, OPTIONAL, INTENT(OUT) :: ierror

`MPI_FINALIZED(FLAG, IERROR)`

LOGICAL FLAG

INTEGER IERROR

This routine returns true if `MPI_FINALIZE` has completed. It is valid to call `MPI_FINALIZED` before `MPI_INIT` and after `MPI_FINALIZE`. This function must always be thread-safe, as defined in Section 12.4.

Advice to users. MPI is “active” and it is thus safe to call MPI functions if `MPI_INIT` has completed and `MPI_FINALIZE` has not completed. If a library has no other way of knowing whether MPI is active or not, then it can use `MPI_INITIALIZED` and `MPI_FINALIZED` to determine this. For example, MPI is “active” in callback functions that are invoked during `MPI_FINALIZE`. (*End of advice to users.*)

8.8 Portable MPI Process Startup

A number of implementations of MPI provide a startup command for MPI programs that is of the form

```
mpirun <mpirun arguments> <program> <program arguments>
```

Separating the command to start the program from the program itself provides flexibility, particularly for network and heterogeneous implementations. For example, the startup script need not run on one of the machines that will be executing the MPI program itself.

Having a standard startup mechanism also extends the portability of MPI programs one step further, to the command lines and scripts that manage them. For example, a validation suite script that runs hundreds of programs can be a portable script if it is written using such a standard startup mechanism. In order that the “standard” command not be confused with existing practice, which is not standard and not portable among implementations, instead of `mpirun` MPI specifies `mpiexec`.

1 While a standardized startup mechanism improves the usability of MPI, the range of
 2 environments is so diverse (e.g., there may not even be a command line interface) that MPI
 3 cannot mandate such a mechanism. Instead, MPI specifies an `mpirexec` startup command
 4 and recommends but does not require it, as advice to implementors. However, if an im-
 5 plementation does provide a command called `mpirexec`, it must be of the form described
 6 below.

7 It is suggested that

```
8     mpiexec -n <numprocs> <program>
```

9
 10 be at least one way to start `<program>` with an initial `MPI_COMM_WORLD` whose group
 11 contains `<numprocs>` processes. Other arguments to `mpirexec` may be implementation-
 12 dependent.

13
 14 *Advice to implementors.* Implementors, if they do provide a special startup command
 15 for MPI programs, are advised to give it the following form. The syntax is chosen in
 16 order that `mpirexec` be able to be viewed as a command-line version of
 17 `MPI_COMM_SPAWN` (See Section 10.3.4).

18 Analogous to `MPI_COMM_SPAWN`, we have

```
19  

  20     mpiexec -n                <maxprocs>  

  21     -soft                    <      >  

  22     -host                    <      >  

  23     -arch                    <      >  

  24     -wdir                    <      >  

  25     -path                    <      >  

  26     -file                    <      >  

  27     -initial-errhandler <      >  

  28     ...  

  29     <command line>
```

30
 31 for the case where a single command line for the application program and its arguments
 32 will suffice. See Section 10.3.4 for the meanings of these arguments. For the case
 33 corresponding to `MPI_COMM_SPAWN_MULTIPLE` there are two possible formats:

34 Form A:

```
35  

  36     mpiexec { <above arguments> } : { ... } : { ... } : ... : { ... }
```

37
 38
 39 As with `MPI_COMM_SPAWN`, all the arguments are optional. (Even the `-n x` argu-
 40 ment is optional; the default is implementation dependent. It might be 1, it might be
 41 taken from an environment variable, or it might be specified at compile time.) The
 42 names and meanings of the arguments are taken from the keys in the `info` argument
 43 to `MPI_COMM_SPAWN`. There may be other, implementation-dependent arguments
 44 as well.

45 Note that Form A, though convenient to type, prevents colons from being program
 46 arguments. Therefore an alternate, file-based form is allowed:

47 Form B:

```
mpiexec -configfile <filename>
```

where the lines of <filename> are of the form separated by the colons in Form A. Lines beginning with '#' are comments, and lines may be continued by terminating the partial line with '\'.
(1
(2
(3
(4
(5
(6

Example 8.11 Start 16 instances of `myprog` on the current or default machine:
(7
(8

```
mpiexec -n 16 myprog
```

Example 8.12 Start 10 processes on the machine called `ferrari`:
(9
(10
(11
(12

```
mpiexec -n 10 -host ferrari myprog
```

Example 8.13 Start three copies of the same program with different command-line arguments:
(13
(14
(15
(16
(17
(18

```
mpiexec myprog infile1 : myprog infile2 : myprog infile3
```

Example 8.14 Start the `ocean` program on five Suns and the `atmos` program on 10 RS/6000's:
(19
(20
(21
(22
(23
(24

```
mpiexec -n 5 -arch sun ocean : -n 10 -arch rs6000 atmos
```

It is assumed that the implementation in this case has a method for choosing hosts of the appropriate type. Their ranks are in the order specified.
(25
(26
(27
(28
(29
(30

Example 8.15 Start the `ocean` program on five Suns and the `atmos` program on 10 RS/6000's (Form B):
(31
(32
(33

```
mpiexec -configfile myfile
```

where `myfile` contains
(34
(35
(36
(37

```
-n 5 -arch sun    ocean  
-n 10 -arch rs6000 atmos
```

(End of advice to implementors.)
(38
(39
(40
(41
(42
(43
(44
(45
(46
(47
(48

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